

EV3 MICROPYTHON

LESSON 4



By **STEMPowering Girls**
stempoweringgirls.org

REVIEW!

Last week, we learned about the ultrasonic sensor and the color sensor.



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GYRO SENSOR



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GYRO SENSOR

The gyro sensor can detect the speed at which it is moving. It is useful for making turns accurate and driving in a straight line.



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SPEED FUNCTION

SPEED FUNCTION

The speed function detects the speed at which the sensor is moving. It returns it in degrees per second.

```
print(gyro.speed())
```



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NOW TRY IT YOURSELF!

CREATE A PROGRAM TO GO FORWARD AT ANY SPEED YOU WANT AND HAVE THE GYRO SENSOR DETECT IT



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ANGLE FUNCTION

ANGLE FUNCTION

The angle function detects the angle that the gyro sensor is at. It returns the degree that sensor is at.

To detect the angle:

```
gyro.angle()
```

To reset the angle:

```
gyro.reset_angle()
```



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NOW TRY IT YOURSELF!

CREATE A PROGRAMING THAT GIVEN THE ANGLE INPUT CAN DO AN ACCURATE TURN.



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